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together analysis and design tools for engineers and researchers who want to design and implement parallel structures in industry Covers Kinematics Dynamics and Control in One Volume The book begins with the representation of motion of robots and the kinematic analysis of parallel manipulators Moving beyond static positioning it then examines a systematic approach to performing Jacobian analysis A special feature of the book is its detailed coverage of the dynamics and control of parallel manipulators. The text examines dynamic analysis using the Newton Euler method the principle of virtual work and the Lagrange formulations Finally the book elaborates on the control of parallel robots considering both motion and force control It introduces various model free and model based controllers and develops robust and adaptive control schemes It also addresses redundancy resolution schemes in detail Analysis and Design Tools to Help You Create Parallel Robots In each chapter the author revisits the same case studies to show how the techniques may be applied. The case studies include a planar cable driven parallel robot part of a promising new generation of parallel structures that will allow for larger workspaces The MATLAB code used for analysis and simulation is available online Combining the analysis of kinematics and dynamics with methods of designing controllers this text offers a holistic introduction for anyone interested in designing and implementing parallel robots Engineering Dimensions, Units, and Conversions Yongjian Gu, 2025-02-27 Engineering Dimensions Units and Conversions delves into the analysis and application of the dimensions units and unit conversions in engineering practical use It demonstrates the importance of dimensional homogeneity and unit consistency Offering a comprehensive exploration of both primary and secondary units the book presents detailed portrayals of various unit systems in both the English system and the International System SI It provides insight into conversion ratios and introduces software based methodologies The book also examines dimensioning in drawings including dimensioning basics and numerous exercises of object and system dimensioning The book will be a valuable reference for practicing engineers and researchers engaged in engineering research and development It will also be of interest to undergraduate and graduate students in 700 Solved Problems In Vector Mechanics for Engineers: Dynamics Joseph F. engineering disciplines Shelley, 1991-04 Suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course It offers the comprehensive solved problem reference in the subject It also provides the student with the problem solving drill **800 Solved Problems** in Vector Mechanics for Engineers Joseph F. Shelley, 1990 Solving Dynamics Problems with Matlab Brian Harper, 2001-11-26 Over the past 50 years Meriam Kraige's Engineering Mechanics Dynamics has established a highly respected tradition of Excellence A Tradition that emphasizes accuracy rigor clarity and applications Now completely revised redesigned and modernized the new fifth edition of this classic text builds on these strengths adding new problems and a more accessible student friendly presentation Solving Dynamics Problems with Matlab If MATLAB is the operating system you need to use for your engineering calculations and problem solving this reference will be a valuable tutorial for your

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