

1.56

$$x(t) = \frac{1}{2} \cos \frac{\pi}{2} t - \cos \pi t$$

$$\ddot{x}(t) = -\frac{\pi^2}{8} \cos \frac{\pi}{2} t + \pi^2 \cos \pi t \neq -\text{constant times } x(t)$$

$\therefore x(t)$  is not harmonic

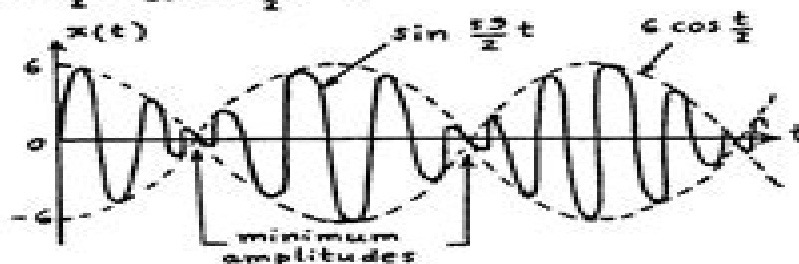
1.57

$$x(t) = x_1(t) + x_2(t) = 3 \sin 30t + 3 \sin 29t$$

$$\text{Since } \sin A + \sin B = 2 \sin \frac{A+B}{2} \cos \frac{A-B}{2},$$

$$x(t) = \left(6 \cos \frac{t}{2}\right) \sin \frac{52}{2} t$$

This equation shows that the amplitude  $\left(6 \cos \frac{t}{2}\right)$  varies with time between a maximum value of 6 and a minimum value of 0. The frequency of this oscillation (beat frequency) is  $\omega_b = 1$ .



Note: Beat frequency is twice the frequency of the term  $6 \cos \frac{t}{2}$  since two peaks pass in each cycle of  $\left(6 \cos \frac{t}{2}\right)$ .

1.58

The resultant motion of two harmonic motions having identical amplitudes ( $X$ ) but slightly different frequencies ( $\omega$  and  $\omega + \delta\omega$ ) is given by Eq. (1.67):

$$x(t) = 2X \cos \left( \omega t + \frac{\delta\omega t}{2} \right) \cos \left( \frac{\delta\omega t}{2} \right)$$

Thus the maximum amplitude of the resultant motion is equal to  $2X$  and the beat frequency is equal to  $\delta\omega$ . From Fig. 1.88, we find that  $2X \approx 5$  mm or  $X = 2.5$  mm and

$$\frac{\delta\omega}{2} = \frac{2\pi}{T_{\text{beat}}} = \frac{2\pi}{T_{\text{major}}} = \frac{2\pi}{2(12.6 - 4.2)} = 0.374 \text{ rad/sec}$$

$$\text{or } \delta\omega = 0.748 \text{ rad/sec and } \omega + \frac{\delta\omega}{2} = \frac{2\pi}{T_{\text{minor}}} = \frac{2\pi}{1} = 6.2832 \text{ rad/sec}$$

Hence  $\omega = 6.2832 - 0.3740 = 5.9092$  rad/sec. Thus the amplitudes of the two motions =  $X = 2.5$  mm and their frequencies are  $\omega = 5.9092$  rad/sec and  $\omega + \delta\omega = 5.9092 + 0.7480 = 6.6572$  rad/sec.

1.59

$$A = 0.05 \text{ m}, \quad \omega = 10 \text{ Hz} = 62.832 \text{ rad/sec}$$

$$\text{period} = \tau = \frac{2\pi}{\omega} = \frac{2\pi}{62.832} = 0.1 \text{ sec}$$

$$\text{maximum velocity} = A\omega = 0.05 \times 62.832 = 3.1416 \text{ m/s}$$

$$\text{maximum acceleration} = A\omega^2 = 0.05 (62.832)^2 = 197.393 \text{ m/s}^2$$

# Mechanical Vibrations Rao 4th Solution Manual

**Tao Wei**



## **Mechanical Vibrations Rao 4th Solution Manual:**

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*Solutions Manual to Accompany Mechanical Vibrations* Francis S. Tse,Ivan E. Morse,Rolland Theodore Hinkle,1978

Books in Print ,1991      *Solutions Manual* Robert Francis Steidel,Steidel,197?      **Books in Print Supplement** ,1994

**Introduction to Nonlinear Aeroelasticity** Grigorios Dimitriadis,2017-05-01 Introduction to Nonlinear Aeroelasticity Introduces the latest developments and technologies in the area of nonlinear aeroelasticity Nonlinear aeroelasticity has become an increasingly popular research area in recent years There have been many driving forces behind this development increasingly flexible structures nonlinear control laws materials with nonlinear characteristics and so on Introduction to Nonlinear Aeroelasticity covers the theoretical basics in nonlinear aeroelasticity and applies the theory to practical problems As nonlinear aeroelasticity is a combined topic necessitating expertise from different areas the book introduces methodologies from a variety of disciplines such as nonlinear dynamics bifurcation analysis unsteady aerodynamics non smooth systems and others The emphasis throughout is on the practical application of the theories and methods so as to enable the reader to apply their newly acquired knowledge Key features Covers the major topics in nonlinear aeroelasticity from the galloping of cables to supersonic panel flutter Discusses nonlinear dynamics bifurcation analysis numerical continuation unsteady aerodynamics and non smooth systems Considers the practical application of the theories and methods Covers nonlinear dynamics bifurcation analysis and numerical methods Accompanied by a website hosting Matlab code Introduction to Nonlinear Aeroelasticity is a comprehensive reference for researchers and workers in industry and is also a useful introduction to the subject for graduate and undergraduate students across engineering disciplines      Solutions Manual to Accompany Applied Mechanical Vibrations David V. Hutton,1981      **Solutions Manual to Accompany Mechanical Vibrations** Francis S. Tse,1978      An Introduction to Mechanical Vibrations Steidel,1989-03-01      **Scientific and Technical Books and Serials in Print** ,1989      **Dynamics of Structure and Foundation - A Unified Approach**

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