

Model predictive control
(MPC)



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graph TD; A[Model predictive control (MPC)] --> B[Finite control set MPC]; A --> C[Continuous control set MPC]; B --> D[Optimal switching vector MPC]; B --> E[Optimal switching sequence MPC]; C --> F[Generalized predictive control]; C --> G[Explicit MPC];
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Finite control set MPC

Continuous control set MPC

Optimal
switching
vector MPC

Optimal
switching
sequence MPC

Generalized
predictive
control

Explicit
MPC

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Model Predictive Control Eduardo F. Camacho, Carlos Bordons, José M. Maestre, 2025-08-10 Model Predictive Control MPC the classic textbook for students and practitioners seeking deep understanding of advanced control systems is now revised updated and reorganized in a streamlined third edition The authors renowned researchers in the field cover an extensive range of topics that embraces the basic and the advanced the theoretical and the applied The book offers advanced undergraduate and graduate students an accessible step by step approach that enables them progressively to grasp and apply the concepts they are studying For instructors this is an invaluable curriculum resource packed with examples and case studies The text features material on commercial MPC convolution models transfer functions state space models and constraints advanced topics robust and stochastic MPC and MPC for nonlinear hybrid large scale and distributed systems and applications a series of case studies in solar energy generation hospital stock control copper mining and aviation along with exercises to help readers assess their progress many with full or partial solutions in a solutions manual downloadable by adopting instructors MATLAB programs to assist with the design aspects of the book and with reproducing some of the examples are included Model Predictive Control third edition s distinctive strength is its real world relevance It is an essential tool for future engineers its focus on practical implementation bridging the gap between academic theory and industrial practice and supplemented by exploration of optimization and algorithm related aspects of MPC ensures a holistic treatment of the subject

Model Predictive Control Baocang Ding, Yuanqing Yang, 2024-03-19 Model Predictive Control Understand the practical side of controlling industrial processes Model Predictive Control MPC is a method for controlling a process according to given parameters derived in many cases from empirical models It has been widely applied in industrial units to increase revenue and promoting sustainability Systematic overviews of this subject however are rare and few draw on direct experience in industrial settings Assuming basic knowledge of the relevant mathematical and algebraic modeling techniques the book s title combines foundational theories of MPC with a thorough sense of its practical applications in an industrial context The result is a presentation uniquely suited to rapid incorporation in an industrial workplace Model Predictive Control readers will also find Two part organization to balance theory and applications Selection of topics directly driven by industrial demand An author with decades of experience in both teaching and industrial practice This book is ideal for industrial control engineers and researchers looking to understand MPC technology as well as advanced undergraduate and graduate students studying predictive control and related subjects

Automotive Model Predictive Control Luigi Del Re, Frank Allgöwer, Luigi Glielmo, Carlos Guardiola, Ilya Kolmanovsky, 2010-03-11 Automotive control has developed over the decades from an auxiliary technology to a key element without which the actual performances emission safety and consumption targets could not be met Accordingly automotive control has been increasing its authority and responsibility at the price of complexity and difficult tuning The progressive evolution has been mainly led by speci

applications and short term targets with the consequence that automotive control is to a very large extent more heuristic than systematic. Product requirements are still increasing and new challenges are coming from potentially huge markets like India and China and against this background there is wide consensus both in the industry and academia that the current state is not satisfactory. Model based control could be an approach to improve performance while reducing development and tuning times and possibly costs. Model predictive control is a kind of model based control design approach which has experienced a growing success since the middle of the 1980s for slow complex plants in particular of the chemical and process industry. In the last decades several developments have allowed using these methods also for fast systems and this has supported a growing interest in its use also for automotive applications with several promising results reported. Still there is no consensus on whether model predictive control with its high requirements on model quality and on computational power is a sensible choice for automotive control.

Process Dynamics and Control Dale E. Seborg, Thomas F. Edgar, Duncan A. Mellichamp, Francis J. Doyle, III, 2016-09-13 The new 4th edition of Seborg's Process Dynamics and Control provides full topical coverage for process control courses in the chemical engineering curriculum emphasizing how process control and its related fields of process modeling and optimization are essential to the development of high value products. A principal objective of this new edition is to describe modern techniques for control processes with an emphasis on complex systems necessary to the development, design and operation of modern processing plants. Control process instructors can cover the basic material while also having the flexibility to include advanced topics.

Explicit Nonlinear Model Predictive Control Alexandra Grancharova, Tor Arne Johansen, 2012-03-22 Nonlinear Model Predictive Control (NMPC) has become the accepted methodology to solve complex control problems related to process industries. The main motivation behind explicit NMPC is that an explicit state feedback law avoids the need for executing a numerical optimization algorithm in real time. The benefits of an explicit solution in addition to the efficient on line computations include also verifiability of the implementation and the possibility to design embedded control systems with low software and hardware complexity. This book considers the multi parametric Nonlinear Programming (mp NLP) approaches to explicit approximate NMPC of constrained nonlinear systems developed by the authors as well as their applications to various NMPC problem formulations and several case studies. The following types of nonlinear systems are considered resulting in different NMPC problem formulations: Nonlinear systems described by first principles models and nonlinear systems described by black box models; Nonlinear systems with continuous control inputs and nonlinear systems with quantized control inputs; Nonlinear systems without uncertainty and nonlinear systems with uncertainties; polyhedral description of uncertainty and stochastic description of uncertainty; Nonlinear systems consisting of interconnected nonlinear sub systems. The proposed mp NLP approaches are illustrated with applications to several case studies which are taken from diverse areas such as automotive mechatronics, compressor control, combustion plant control, reactor control, pH maintaining system control, cart and spring system control and diving computers.

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Exam Preparation Career Growth Professional Development IT Security Cloud Engineering IT Skills IT Certifications **Journal of Guidance, Control, and Dynamics**, 2007 Predictive Control Jan Marian Maciejowski, 2002 Model predictive control is an indispensable part of industrial control engineering and is increasingly the method of choice for advanced control applications Jan Maciejowski's book provides a systematic and comprehensive course on predictive control suitable for final year students and professional engineers The first book to cover constrained predictive control the text reflects the true use of the topic in industry Control System Design Graham Clifford Goodwin, Stefan F. Graebe, Mario E. Salgado, 2001 For both undergraduate and graduate courses in Control System Design Using a how to do it approach with a strong emphasis on real world design this text provides comprehensive single source coverage of the full spectrum of control system design Each of the text's 8 parts covers an area in control ranging from signals and systems Bode Diagrams Root Locus etc to SISO control including PID and Fundamental Design Trade Offs and MIMO systems including Constraints MPC Decoupling etc

The Second Shell Process Control Workshop David M. Prett, Carlos E. García, Brian L. Ramaker, 1990 **Model Predictive Control - Theory and Applications** Constantin Voloşencu, 2023-07-12 The book presents some recent specialized theoretical and practical works in the field of process control based on the model predictive control MPC method It includes seven chapters that present studies on the application of MPC in various technical processes such as the atmospheric plasma spray process permanent magnet synchronous motors monitoring of the pose of a walking person monitoring of the heat treatment process of raw materials discrete event processes control of passenger vehicles and natural gas sweetening processes Chapters include examples and case studies from researchers in the field This volume provides readers with new solutions and answers to questions related to the emerging applications of MPC and their implementation

Advances in Automotive Control 2001 U. Kiencke, G. L. Gissinger, 2001 This Proceedings contains the papers presented at the Third IFAC Workshop on ADVANCES IN AUTOMOTIVE CONTROL held in Karlsruhe Germany on 28-30 March 2001 As the subject indicates the aim of this workshop was to discuss not only the latest advances related to motor vehicles but also and more generally to exchange ideas between academic partners car manufacturers and subcontractors The plenary lectures are of great importance and the thematic sessions in the different sections are the essence of such workshops However the discussions between experts in the different fields the meetings between people from industry universities and public or private laboratories as well as the resulting exchange of ideas are as important Research is often

criticized for providing merely theoretical results and for the insufficient number of its applications. The motor vehicle industry offers a wide field of applications in which we can validate all techniques, tools and methods. This allows us to be involved in all the areas of fundamental research in all the different possible approaches from fundamental research to technology transfer and to observe the actual effects of our results. The increase in road traffic was a major problem of the last century. It is clear that one of the challenges of the XXIst century will be to improve driving safety and comfort. The sessions in the Proceedings volume are divided as follows: Driveline control, Driveline modelling, Vehicle dynamics I and II, Electronic architecture, Intelligent components, Engine control I and II, Engine modelling, Modelling of combustion and turbocharging, Diagnostics and Subsystems. The quality of the papers and the diversity of their origins clearly show the interest taken in this key sector of our research and industry.

Model Based Control Paul Serban Agachi, 2006-11-10. Filling a gap in the literature for a practical approach to the topic, this book is unique in including a whole section of case studies presenting a wide range of applications from polymerization reactors and bioreactors to distillation column and complex fluid catalytic cracking units. A section of general tuning guidelines of MPC is also present. These thus aid readers in facilitating the implementation of MPC in process engineering and automation. At the same time, many theoretical, computational and implementation aspects of model based control are explained with a look at both linear and nonlinear model predictive control. Each chapter presents details related to the modeling of the process as well as the implementation of different model based control approaches and there is also a discussion of both the dynamic behaviour and the economics of industrial processes and plants. The book is unique in the broad coverage of different model based control strategies and in the variety of applications presented. A special merit of the book is in the included library of dynamic models of several industrially relevant processes which can be used by both the industrial and academic community to study and implement advanced control strategies.

Zoltan K Nagy received his PhD from Babes Bolyai University of Cluj where he worked as a lecturer until 2005. Before taking up his current appointment as a faculty member at Loughborough University, UK, he was NATO research fellow and visiting lecturer at the University of Illinois at Urbana Champaign and research associate at the University of Stuttgart, University of Heidelberg and ETH Zurich. His main research interest is in the model based control and optimization of chemical processes. He worked on industrial implementation of model based control strategies with companies such as BASF and ABB and has published over 80 papers in the field.

Arpad Imre Lucaci received his MSc and PhD degrees in chemical engineering from Babes Bolyai University of Cluj Napoca in 1985 and 1999 respectively. Since 1988 he has worked in the Chemical Engineering Department of BBU Cluj Napoca, Romania and spent research stays at University of Stuttgart 1994 and ETH Zurich in 2002 and 2003. His main research fields are mathematical modeling, simulation and optimization in process industries on which he has published over 20 scientific papers.

Cristea Vasile Mircea graduated the Faculty of Electrotechnics, Romania with specialization on process control and computer science and holds a PhD degree in process.

control After 8 years spent in industry he is at present Associate Professor at Babes Bolyai University Cluj Napoca his interests lie in systems theory chemical process control advanced process control data acquisition and control linear and nonlinear model based predictive control and fuzzy control He was director of CNCSIS Projects and has published 3 books as well as over 55 scientific papers Professor Paul Serban Agachi graduated in 1970 in Control Engineering at the Politehnica University of Bucharest Obtained his Ph D in Chemical Engineering from the University Petroleum Gas Ploiesti Romania Professional experience design engineer system analyst researcher in fuel cells process modeling optimization and control At present professor of Process Control at the Department of Chemical Engineering of Babes Bolyai University Cluj Napoca and member of the Academy of Technical Sciences of Romania He has been visiting associate at California Institute of Technology invited professor at E tv s Lorand University UNESCO Higher Education consultant He has published 8 books and 96 scientific papers

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UKACC International Conference on Control '98, 1-4 September 1998, Venue, University of Wales, Swansea, UK ,1998

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