



Line Follower Robot Using Pid Control

G Thomas



Line Follower Robot Using Pid Control:

Industrial Networks and Intelligent Systems Nguyen-Son Vo, Hoai-An Tran, 2023-10-30 This book constitutes the refereed proceedings of the 9th EAI International Conference on Industrial Networks and Intelligent Systems INISCOM 2023 held in Ho Chi Minh City Vietnam during August 2 3 2023 The 23 full papers were selected from 55 submissions and are organized thematically in tracks on telecommunications systems and networks information processing and data analysis industrial networks and intelligent systems security and privacy *Intelligent Technologies: Design and Applications for Society* Vladimir Robles-Bykbaev, Josefa Mula, Gilberto Reynoso-Meza, 2023-01-31 This book is oriented towards applications and perspectives on future developments connected to intelligent technologies Specifying topics connected to industry mobility telecommunications biomechanics among others The innovative character of the text allows relating technical experiences and advances that seek to improve the implication of new technologies at local national and regional levels demonstrating the advances towards the different fields of knowledge in the area of engineering The potential readers of this work would be master and doctorate students professors researchers in the field of new technologies and companies connected to the development of engineering The texts serve to illustrate new procedures new cases and new techniques for the optimization of systems that optimize social progress Intelligent Electrical Systems and Industrial Automation Sanjoy Mondal, Vincenzo Piuri, João Manuel R. S. Tavares, 2024-11-28 This book features high quality research papers presented at the International Conference on Intelligent Electrical Systems Industrial Automation IESIA 2024 organized by Department of Electrical Engineering Electrical and Electronics Engineering Institute of Engineering Management Kolkata India during April 5 7 2024 The volume presents diverse range of topics including smart sensors automation control algorithms energy efficient solutions and real time data analytics *Proceedings of Mechanical Engineering Research Day 2017* Mohd Fadzli Bin Abdollah, Tee Boon Tuan, Mohd Azli Salim, Mohd Zaid Akop, Rainah Ismail, Haslinda Musa, 2017-05-29 This e book is a compilation of papers presented at the Mechanical Engineering Research Day 2017 MERD 17 Melaka Malaysia on 30 March 2017 **Proceedings of SAI Intelligent Systems Conference (IntelliSys) 2016** Yaxin Bi, Supriya Kapoor, Rahul Bhatia, 2017-08-22 These proceedings of the SAI Intelligent Systems Conference 2016 IntelliSys 2016 offer a remarkable collection of papers on a wide range of topics in intelligent systems and their applications to the real world Authors hailing from 56 countries on 5 continents submitted 404 papers to the conference attesting to the global importance of the conference s themes After being reviewed 222 papers were accepted for presentation and 168 were ultimately selected for these proceedings Each has been reviewed on the basis of its originality novelty and rigorousness The papers not only present state of the art methods and valuable experience from researchers in the related research areas they also outline the field s future development **Line Follower Robot with PID Controller Approach Ziegler Nichols Method** , 2015

Line Followers Robot Using PID Controller Abd Azrin Firdaus A Rahim, 2008 Robot becomes widely used in industrial due

to their characteristics Robot able to work in 24 hours continuously without feeling tired unlike human that confine to certain time The cost to setup the robot nowadays becomes more affordable and their long term prospect is bright judging from their capacity to perform But in reality there is no robot able to function perfectly and still making error A better controller needed here to allow the robot performs efficiently and make less error This project try to implement a PID controller on mobile robot to see whether the robot perform efficiently This mobile robot has a line tracking module where it will follow the track that made from black tape This is area where the PID implemented the robot will be able to follow the black tape effectively and moving along the track smoothly

Proceedings of the 11th National Technical Seminar on Unmanned System Technology 2019 Zainah Md Zain,Hamzah Ahmad,Dwi Pebrianti,Mahfuzah Mustafa,Nor Rul Hasma Abdullah,Rosdiyana Samad,Maziyah Mat Noh,2020-07-07 This book includes research papers from the 11th National Technical Symposium on Unmanned System Technology Covering a number of topics including intelligent robotics novel sensor technology control algorithms acoustics signal processing imaging techniques biomimetic robots green energy sources and underwater communication backbones and protocols it will appeal to researchers developing marine technology solutions and policy makers interested in technologies to facilitate the exploration of coastal and oceanic regions

Foundations of Fuzzy Control Jan Jantzen,2007-04-02 Fuzzy logic is key to the efficient working of many consumer industrial and financial applications Providing a brief history of the subject as well as analysing the system architecture of a fuzzy controller this book gives a full and clearly set out introduction to the topic As an essential guide to this subject for many engineering disciplines Foundations of Fuzzy Control successfully exploits established results in linear and non linear control theory It presents a full coverage of fuzzy control from basic mathematics to feedback control all in a tutorial style In particular this book Systematically analyses several fuzzy PID Proportional Integral Derivative control systems and state space control and also self learning control mechanisms Sets out practical worked through problems examples and case studies to illustrate each type of control system Provides an accompanying Web site that contains downloadable Matlab programs This book is an invaluable resource for a broad spectrum of researchers practitioners and students in engineering In particular it is especially relevant for those in mechanical and electrical engineering as well as those in artificial intelligence machine learning bio informatics and operational research It is also a useful reference for practising engineers working on the development of fuzzy control applications and system architectures

Mechanical and Electronics Engineering III Han Zhao,2011-10-27 Selected peer reviewed papers from the 2011 3rd International Conference on Mechanical and Electronics Engineering ICMEE 2011 September 23 25 2011 Hefei China

Feedback Control of Dynamic Bipedal Robot Locomotion Eric R. Westervelt,2007-06-26 The authors present cutting edge systematic methods for achieving stable agile and efficient locomotion in bipedal machines

Fuzzy Logic and NeuroFuzzy Applications Explained Constantin Von Altrock,1995 Disks contain simulation edition of fuzzyTECH development software from Inform Software corporation

Control Architecture for Vision Guided Tracking Sameer Milind Kelkar,2007 **Path Follower Mobile Robot Using PID Controller** Muhammad Mazlan,2008 This project is about path follower mobile robot using PID Controller As we know the PID controller is a generic control loop feedback mechanism widely used in industrial control system The controller corrects the error that makes the mobile robot moving out of track This project concentrates in the development path follower mobile robot which is moving in square path with straight line and turn 90 degree and integrating the PID Controller into steering path for the path follower mobile robot to make the mobile robot moving smooth straight line and turning 90degree At the end of this project also discuss about the comparison between controllers that could integrate into the mobile robot system *Introduction to Applied Fuzzy Electronics* Ahmad M. Ibrahim,1997 This book provides a self contained compact introduction to fuzzy logic from an applied electronics point of view It presents fuzzy electronics as a generalization of digital electronics with the goal of making fuzzy logic easily accessible to practicing engineers and students alike *Microcomputer Applications* ,1990 **Smart Structures and Materials** ,1995 IEEE Intelligent Vehicles Symposium ,2005 **Journal of Dynamic Systems, Measurement, and Control** ,1989 Proceedings of the 1993 American Control Conference ,1993

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