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Richard C. Dorf • Robert H. Bishop



 Pearson

Modern Control Systems 11th Edition

Saurabh Mani Tripathi



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been developed in the frequency and time domains It provides coverage of classical control employing root locus design frequency and response design using Bode and Nyquist plots It also covers modern control methods based on state variable models including pole placement design techniques with full state feedback controllers and full state observers Many examples throughout give students ample opportunity to apply the theory to the design and analysis of control systems Incorporates computer aided design and analysis using MATLAB and LabVIEW MathScript *Government Reports Announcements & Index ,1988*

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